

SOME CURVATURE IDENTITIES ON HYPERKÄHLER MANIFOLDS

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ABSTRACT. The object of the present paper is to study some curvature identities on hyperKähler manifold which is locally symmetric. Also, we study conformal flatness, Bochner flatness and generalised W_2 -flatness of a hyperKähler manifold. Finally, we gave some examples of a hyperKähler manifold.

1. INTRODUCTION

A hyperKähler manifold [15] is a Riemannian $4n$ -manifold with a family of almost complex structures which act under composition like the multiplication, pure-imaginary, unit quaternions and which are covariantly constant with respect to the Levi-Civita connection. If we only requisite that these almost complex structures exist locally and that the Levi-Civita connection preserves this family generally, then we obtain a quaternionic Kähler structure, at least if $n \geq 2$. Thus hyperKähler manifolds are a special case of quaternionic Kähler manifolds. Although, note that quaternionic Kähler manifold need not be Kähler.

Remember that a Riemannian manifold which has just one such automorphism is called a Kähler manifold. The name “hyperKähler”, which established with E. Calabi [8], is a proper description-the metric is Kählerian for several complex structures-even though it does recall Grassmann’s “hypercomplex numbers” rather than Hamilton’s quaternions. There is, however, an essential difference between Kähler and hyperKähler manifolds. A Kähler metric on a given complex manifold can be modified to another one simply by adding a hermitian form $\partial\bar{\partial}f$ for an arbitrary sufficiently small C^∞ function f . Thus the space of Kähler metrics is infinite dimensional. It is also easy to find examples of Kähler manifolds. Any complex submanifold of CP_n inherits a Kähler metric and so simple writing down algebraic equations for a projective variety gives a vast number of examples.

By contrast, hyperKähler metrics are much more rigid. On a compact manifold, if one such metric exists, then up to isometry there is only a finite dimensional

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space of them. Nor is it easy to find examples. Obviously, we will never find them as quaternionic submanifolds of the quaternionic projective space $\mathbb{H}P_n$ [6].

The idea of a hyperKähler manifold arose first in 1955 with M. Berger's classification of the holonomy groups of Riemannian manifolds. On a hyperKähler manifold, parallel translation preserves I, J and K (since they are covariant constant) and so the holonomy group is contained in both orthogonal group O_{4n} and the group $GL(n, \mathbb{H})$ of quaternionic invertible matrices (i.e., those linear transformations which commute with right multiplication by i, j and k). The maximal such intersection in SP_n , the group of $n \times n$ quaternionic unitary matrices. This group performed in Berger's list.

The group SP_n is also an intersection of U_{2n} and $SP(2n, C)$, the linear transformations of C^{2n} which preserve a non-degenerate skew form. Thus a hyperKähler manifold is naturally a complex manifold with a holomorphic symplectic form. One can see explicitly by taking the three Kähler two-forms, $\omega_1(X, Y) = g(IX, Y)$, $\omega_2(X, Y) = g(JX, Y)$, $\omega_3(X, Y) = g(KX, Y)$ for $X, Y \in TM$, defined for the complex structures I, J and K . As to complex structures I, J and K , the complex form $\omega_+ = \omega_2 + i\omega_3$ is non-degenerate and covariant constant, hence it is closed and holomorphic.

Now, also we define the generalised W_2 -curvature tensor ($4n > 8$) as follows:

$$\overline{W}_2(X, Y)Z = aR(X, Y)Z + \left(b + \frac{c}{4n-7}\right)[g(X, Z)QY - g(Y, Z)QX], \quad (1.1)$$

where $a, b, c \neq 0$. In particular, if $a = 1, b = 0, c = 1$; then it reduces to W_2 -curvature tensor. Again if $b = 0$, we call the $\overline{W}_2$ tensor as quasi- W_2 tensor and is denoted by $\widetilde{W}_2$. So a manifold is generalised W_2 -flat if $g(\overline{W}_2(X, Y)Z, W) = 0$.

The interest in some curvature identities on hyperKähler manifold is motivated by our study [13] and [15] of hyperKähler manifold and hypercomplex structures in $4n$ -dimensional Riemannian manifolds, which is locally symmetric, conformally flat, Bochner flat and generalised W_2 -flat.

2. PRELIMINARIES

Let (M, g) be a Riemannian manifold with I, J, K compatible almost complex structures parallel for the Levi-Civita connection and with $IJ = K = -JI$. Consequently, (a) I, J, K are Integrable, (b) $\omega_1 = g(I\cdot, \cdot)$ etc. are symplectic forms. Let $\mathbb{H} = \mathbb{R}^4$ with basis $\{1, i, j, k\}$, $i^2 = -1 = j^2 = k^2$, quaternion division algebra. In $\mathbb{H}^n$, $Iq = -qi$ holds, with standard inner product. We also know $SP_1 = SU_2 = \{ai + bj + ck : a^2 + b^2 + c^2 = 1\}$ acts on the right. $SP_n = \{A \in M_n(\mathbb{H}) \mid \overline{A}^T A = 1_n\}$ is centraliser in SO_{4n} of SP_1 .

A hyperKähler manifold is a Riemannian $4n$ -manifold with holonomy in SP_n .

Now, we have the following propositions:

Proposition 2.1. [14] *A hyperKähler manifold M is a complex manifold with a holomorphic symplectic form. Conversely, any compact Kähler manifold [10] with a holomorphic symplectic form is hyperKähler.*

Proposition 2.2. [14] *A hyperKähler manifold is a C^∞ Riemannian manifold together with three covariantly constant orthogonal endomorphisms I, J and K of the tangent bundle which satisfy the quaternionic relations $I^2 = J^2 = K^2 = IJK = -1$.*

Note that, I, J and K give each tangent space the structure of a quaternionic vector space, so the dimension of a hyperKähler manifold is divisible by 4. Since I, J and K are covariantly constant, a parallel transport commutes with the quaternionic multiplication and so the holonomy group is contained in $O_{4n} \cap GL_n(\mathbb{H}) \cong SP_n$, the group of quaternionic unitary $n \times n$ matrices. In particular, since $SP_n \subseteq SU_{2n}$ every hyperKähler manifold is Calabi-Yau [9]. Assume that M is an almost hypercomplex manifold. Define the Nijenhuis tensor N of I, J and K by

$$\begin{aligned} N_I(X, Y) &= [IX, IY] - I[IX, Y] - I[X, IY] - [X, Y], \\ N_J(X, Y) &= [JX, JY] - J[JX, Y] - J[X, JY] - [X, Y], \text{ and} \\ N_K(X, Y) &= [KX, KY] - K[KX, Y] - K[X, KY] - [X, Y], \end{aligned}$$

for all vector fields X, Y . M is said to be hypercomplex if $N_I = N_J = N_K = 0$. Suppose that g is a pseudo Riemannian metric on M satisfying the condition

$$\begin{aligned} g(IX, Y) + g(X, IY) &= 0, \\ g(JX, Y) + g(X, JY) &= 0, \\ g(KX, Y) + g(X, KY) &= 0, \end{aligned} \tag{2.1}$$

for $X, Y \in \chi(M)$. Define the 2-forms $\tilde{I}(X, Y) = g(X, IY)$, $\tilde{J}(X, Y) = g(X, JY)$, $\tilde{K}(X, Y) = g(X, KY)$ for all $X, Y \in \chi(M)$. M is said to be hyperKähler manifold if it is a hypercomplex and the respective 2-forms are closed and $\nabla I = \nabla J = \nabla K = 0$, where ∇ is the Levi-Civita connection on M are equivalent.

3. MAIN RESULTS OF SOME CURVATURE IDENTITIES ON HYPERKÄHLER MANIFOLDS

We are investigated some properties of curvature tensors and Ricci tensors of hyperKähler manifold. Let M be a hyperKähler manifold and R denotes the curvature tensor of M .

Theorem 3.1. *The curvature tensor R satisfies*

$$\begin{aligned}
(i) & R(X, Y)IZ = IR(X, Y)Z, \\
(ii) & R(IX, IY)Z = R(X, Y)Z, \\
(iii) & R(IX, Y)Z + R(X, IY)Z = 0, \\
(iv) & \tilde{R}(IX, IY, IZ, IW) = \tilde{R}(X, Y, Z, W), \\
(v) & \tilde{R}(IX, Y, IZ, W) = \tilde{R}(X, IY, Z, IW), \\
(vi) & \tilde{R}(X, Y, IZ, JW) = -\tilde{R}(IX, IY, Z, IJW), \\
(vii) & \tilde{R}(IX, IY, JZ, JW) = \tilde{R}(X, Y, IJZ, IJW),
\end{aligned}$$

where $\tilde{R}(X, Y, Z, W) = g(R(X, Y)Z, W)$.

Proof. (i) Since I is parallel, i.e., $(\nabla_X I)(Y) = 0$, we get

$$\nabla_X I(Y) = I(\nabla_X Y).$$

Now,

$$\begin{aligned}
R(X, Y)I(Z) &= \nabla_X \nabla_Y I(Z) - \nabla_Y \nabla_X I(Z) - \nabla_{[X, Y]} I(Z) \\
&= \nabla_X I(\nabla_Y Z) - \nabla_Y I(\nabla_X Z) - I(\nabla_{[X, Y]}(Z)) \\
&= I(\nabla_X \nabla_Y Z) - I(\nabla_Y \nabla_X Z) - I(\nabla_{[X, Y]} Z) \\
&= I(R(X, Y)Z).
\end{aligned}$$

(ii) Since $g(R(X, Y)V, U) = g(R(U, V)Y, X)$, we have

$$\begin{aligned}
g(R(IX, IY)V, U) &= g(R(U, V)IY, IX) \\
&= g(I(R)(U, V)Y, IX) \\
&= -g(R(U, V)Y, I^2(X)), \text{ [since } g(IX, Y) = -g(X, IY)] \\
&= g(R(U, V)Y, X), \text{ [since } I^2 = J^2 = K^2 = -1 \\
&\quad \text{and } IJ = -K = JI] \\
&= g(R(X, Y)V, U).
\end{aligned}$$

Hence, $R(IX, IY)V = R(X, Y)V$.

(iii) Putting $X = IX$ in (ii) we obtain (iii).

(iv) Now,

$$\begin{aligned}
g(R(IX, IY)IZ, IW) &= -g(I(R)(IX, IY)IZ, W), \\
&\quad \text{[since } g(IX, Y) = -g(X, IY)] \\
&= -g(R(IX, IY)Z, W) \\
&= g(R(X, Y)Z, W), \\
&\quad \text{[using } g(R(IX, IY)V, U) = g(R(X, Y)V, U)]
\end{aligned}$$

Therefore, $\tilde{R}(IX, IY, IZ, IW) = \tilde{R}(X, Y, Z, W)$.

(v) Setting $Y = IY$, $W = IW$ in (iv) we get (v).

(vi) Putting $X = IX$, $Y = IY$, $W = KW$, where $IJ = K = -JI$ in equation (iv) then we obtain

$$\tilde{R}(X, Y, IZ, JW) = -\tilde{R}(IX, IY, Z, IJW).$$

(vii) Again putting $Z = KZ$, $W = KW$, where $IJ = K = -JI$ in equation (iv) then we have $\tilde{R}(IX, IY, JZ, JW) = \tilde{R}(X, Y, IJZ, IJW)$. $\square$

Remark 3.2. Accordingly, Theorem 3.1 holds for operators J, K . Since $I^2 = J^2 = K^2 = -1$ and $IJ = -K = JI$, so the above curvature identities also hold for the operators IJ and JI .

Let S be the Ricci tensor of M , i.e.,

$$S(Y, Z) = \text{trace}\{X \rightarrow R(X, Y, Z)\} = \sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, Y, Z, e_i),$$

where $\{e_1, e_2, \dots, e_n\}$ is an orthonormal basis for M and $\epsilon_i = g(e_i, e_i) = 1$.

Theorem 3.3. *The Ricci tensor of a hyperKähler manifold satisfies*

$$\begin{aligned} (i) S(IX, IY) &= S(X, Y), \\ (ii) S(IX, Y) + S(X, IY) &= 0. \end{aligned}$$

Proof.

$$\begin{aligned} S(IX, IY) &= \text{trace}\{Z \rightarrow R(Z, IX)IY\} \\ &= \text{trace}\{IZ \rightarrow R(IZ, IX)IY\} \\ &= \text{trace}\{IZ \rightarrow R(Z, X)IY\}, \text{ [by (ii) of Theorem 3.1]} \\ &= \text{trace}\{IZ \rightarrow IR(Z, X)Y\}, \text{ [since } IR = RI] \\ &= \text{trace}\{Z \rightarrow R(Z, X)Y\} \\ &= S(X, Y), \end{aligned}$$

which proves (i).

Now setting $X = IY$ in (i) we obtain (ii). $\square$

Remark 3.4. In parallel, Theorem 3.3 holds for the operators J, K . Since $I^2 = J^2 = K^2 = -1$ and $IJ = -K = JI$, so the above Ricci tensor of a hyperKähler manifold also satisfy for the operators IJ and JI .

Theorem 3.5. *For a hyperKähler manifold of dimension $4n$ the following relation holds, i.e., $\sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, I(e_i), X, I(Y)) = 0$.*

Proof. We have

$$\begin{aligned}
S(X, Y) &= \sum_{i=1}^{4n} \epsilon_i g(R(e_i, X)Y, e_i) \\
&= - \sum_{i=1}^{4n} \epsilon_i g(R(I(e_i), I(X))Y, e_i) \\
&= - \sum_{i=1}^{4n} \epsilon_i g(R(e_i, Y)I(X), I(e_i)) \\
&= - \sum_{i=1}^{4n} \epsilon_i g(R(Y, e_i)I(e_i), I(X)) \\
&= \sum_{i=1}^{4n} \epsilon_i g(R(Y, e_i)I(X), I(e_i)) \\
&= \sum_{i=1}^{4n} \epsilon_i g(R(I(X), e_i)Y, I(e_i)) + \sum_{i=1}^{4n} \epsilon_i g(R(Y, I(X))e_i, I(e_i)), \\
&\quad \text{[using Bianchi's identities]} \\
&= - \sum_{i=1}^{4n} \epsilon_i g(R(e_i, I(X))Y, I(e_i)) - \sum_{i=1}^{4n} \epsilon_i g(R(I(X), Y)e_i, I(e_i)) \\
&= \sum_{i=1}^{4n} \epsilon_i g(I(R)(e_i, I(X))Y, e_i) + \sum_{i=1}^{4n} \epsilon_i g(I(R)(I(X), Y)e_i, e_i) \\
&= \sum_{i=1}^{4n} \epsilon_i g(R(e_i, I(X))I(Y), e_i) + \sum_{i=1}^{4n} \epsilon_i g(R(I(X), Y)I(e_i), e_i) \\
&= S(IX, IY) - \sum_{i=1}^{4n} \epsilon_i g(R(Y, I(X))I(e_i), e_i) \\
&= S(X, Y) + \sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, I(e_i), X, I(Y)).
\end{aligned}$$

So this implies, $\sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, I(e_i), X, I(Y)) = 0$. □

Remark 3.6. Comparably, Theorem 3.5 holds for the operators J, K . Since $I^2 = J^2 = K^2 = -1$ and $IJ = -K = JI$, so the above global form of curvature tensors

of a hyperKähler manifold also satisfy for the operators IJ and JI , i.e.

$$\begin{aligned} (i) \quad & \sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, J(e_i), X, J(Y)) = 0. \\ (ii) \quad & \sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, IJ(e_i), X, IJ(Y)) = 0. \\ (iii) \quad & \sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, JI(e_i), X, JI(Y)) = 0. \end{aligned}$$

3.1. Conformal flatness of hyperKähler manifold. Since any pseudo-Riemannian as well as Riemannian manifold of dimension 3 is conformally flat, we are focused in dimension $4n \geq 4$. Utilizing the identities from the previous section, we prove the following theorem.

Theorem 3.7. *Let M be a conformally flat hyperKähler manifold. Then*

- (i) *M is locally flat if $\dim M \geq 4$,*
- (ii) *M is locally symmetric and its scalar curvature vanishes identically if $\dim M = 4$.*

Proof. By the vanishing of conformal curvature tensor, we have

$$\begin{aligned} \tilde{R}(X, Y, Z, W) = & \frac{1}{2n-2} [-g(X, Z)S(Y, W) - g(Y, W)S(X, Z) + g(X, W)S(Y, Z) \\ & + g(Y, Z)S(X, W)] - \frac{r}{(2n-1)(2n-2)} [g(X, Z)g(Y, W) \\ & - g(X, W)g(Y, Z)], \end{aligned} \quad (3.1)$$

r being the scalar curvature of M . From the above equation with the help of Theorem 3.3 and Theorem 3.1, we get

$$\sum_{i=1}^{4n} \epsilon_i \tilde{R}(e_i, I(e_i), Z, I(W)) = -\frac{2}{n-1} S(Z, W) - \frac{r}{(2n-1)(n-1)} g(Z, W).$$

Then using the result of Theorem 3.5, we obtain

$$S(Z, W) = -\frac{r}{2(2n-1)} g(Z, W). \quad (3.2)$$

Now setting $Z = W = e_i, 1 \leq i \leq n$ and summing over i then from Equation (3.2), we have $(4n-1)r = 0$, where $r = \sum_{i=1}^{4n} \epsilon_i S(e_i, e_i)$. Then this implies $r = 0$, when $4n \geq 4$. Now putting the value of $r = 0$ in the Equation (3.2), we get $S = 0$.

So from Equation (3.1) it follows that the manifold is locally flat. Now, also if $4n = 4$ then $r = 0$, then its scalar curvature vanishes identically. Next we proof the manifold is locally symmetric. Now we assume that conformally flatness implies,

$$(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) = \frac{1}{6} [(X_r)g(Y, Z) - (Y_r)g(X, Z)]. \quad (3.3)$$

Putting $r = 0$ in the Equation (3.3), we obtain

$$(\nabla_X S)(Y, Z) = (\nabla_Y S)(X, Z). \quad (3.4)$$

On the other hand, from Theorem 3.3 it follows that

$$(\nabla_X S)(Y, I(Z)) + (\nabla_X S)(Z, I(Y)) = 0. \quad (3.5)$$

Using the equality and the Equation (3.4), we get

$$(\nabla_X S)(Y, I(Z)) + (\nabla_Y S)(Z, I(X)) = 0. \quad (3.6)$$

Applying the result of the Theorem 3.3 on the above equation, we obtain $\nabla S = 0$. Now from the Equation (3.1) and $\nabla S = 0$, implies that $\nabla R = 0$, i.e., the manifold is locally symmetric. $\square$

From Theorem 3.7, we have the following Corollary:

Corollary 3.8. A conformally flat hyperKähler manifold of dimension $4n$ is an Einstein manifold.

3.2. Bochner flatness and generalised W_2 -flatness of hyperKähler manifold. The notion of Bochner curvature tensor [2] is defined by:

$$\begin{aligned} B(X, Y)Z = & R(X, Y)Z - \frac{1}{2n+4}[g(Y, Z)QX - g(X, Z)QY + S(Y, Z)X \\ & - S(X, Z)Y + g(IY, Z)QIX - g(IX, Z)QIY + S(IY, Z)IX \\ & - S(IX, Z)IY - 2S(IX, Y)IZ - 2g(IX, Y)QIZ] \\ & + \frac{r}{(2n+2)(2n+4)}[g(Y, Z)X - g(X, Z)Y + g(IY, Z)IX \\ & - g(IX, Z)IY - 2g(IX, Y)IZ], \end{aligned} \quad (3.7)$$

where Q is the Ricci operator, defined by $g(QX, Y) = S(X, Y)$ and n is the dimension of the manifold. Moreover a manifold is Bochner flat if $\tilde{B}(X, Y, Z, U) = g(B(X, Y)Z, U) = 0$.

Theorem 3.9. A Bochner flat hyperKähler manifold is an Einstein manifold.

Proof. Taking inner product in the Equation (3.7) by W , we get

$$\begin{aligned} g(B(X, Y)Z, W) = & \tilde{R}(X, Y, Z, W) - \frac{1}{2n+4}[g(Y, Z)S(X, W) - g(X, Z)S(Y, W) \\ & + S(Y, Z)g(X, W) - S(X, Z)g(Y, W) + g(IY, Z)S(IX, W) \\ & - g(IX, Z)S(IY, W) + S(IY, Z)g(IX, W) - S(IX, Z)g(IY, W) \\ & - 2S(IX, Y)g(IZ, W) - 2g(IX, Y)S(IZ, W)] \\ & + \frac{r}{(2n+2)(2n+4)}[g(Y, Z)g(X, W) - g(X, Z)g(Y, W) \\ & + g(IY, Z)g(IX, W) - g(IX, Z)g(IY, W) - 2g(IX, Y)g(IZ, W)]. \end{aligned} \quad (3.8)$$

Now as the manifold is Bochner flat then the above equation reduces to

$$\begin{aligned}\tilde{R}(X, Y, Z, W) = & \frac{1}{2n+4} [g(Y, Z)S(X, W) - g(X, Z)S(Y, W) + S(Y, Z)g(X, W) \\ & - S(X, Z)g(Y, W) + g(IY, Z)S(IX, W) - g(IX, Z)S(IY, W) \\ & + S(IY, Z)g(IX, W) - S(IX, Z)g(IY, W) - 2S(IX, Y) \\ & g(IZ, W) - 2g(IX, Y)S(IZ, W)] - \frac{r}{(2n+2)(2n+4)} [g(Y, Z) \\ & g(X, W) - g(X, Z)g(Y, W) + g(IY, Z)g(IX, W) - g(IX, Z) \\ & g(IY, W) - 2g(IX, Y)g(IZ, W)].\end{aligned}\quad (3.9)$$

Setting $X = e_i, Y = Ie_i, Z = Z$ and $W = IW$ in the above equation and taking summation over $i, 1 \leq i \leq n$ and also using the result of the Theorem 3.5, we obtain

$$S(Z, W) = -\frac{r}{2n+6}g(Z, W). \quad (3.10)$$

Hence the proof. $\square$

From Theorem 3.9 we have the following Corollary:

Corollary 3.10. A Bochner flat hyperKähler manifold is locally flat.

Proof. Taking $Z = W = e_i$ in the above equation and summing over $i, 1 \leq i \leq n$ we obtain

$$r = 0, \text{ provided } 3n + 6 \neq 0. \quad (3.11)$$

Then the Equation (3.10) becomes

$$S(Z, W) = 0. \quad (3.12)$$

So the manifold is locally flat. $\square$

Theorem 3.11. A generalised W_2 -flat hyperKähler manifold is Ricci flat, provided $a \neq (b + \frac{c}{4n-7})$.

Proof. Taking inner product in the Equation (1.1) by W , we get

$$\begin{aligned}g(\overline{W}_2(X, Y)Z, W) = & a\tilde{R}(X, Y, Z, W) + \left(b + \frac{c}{4n-7}\right) [g(X, Z)S(Y, W) \\ & - g(Y, Z)S(X, W)].\end{aligned}\quad (3.13)$$

Now as the manifold is $\overline{W}_2$ -flat then the above equation reduces to

$$a\tilde{R}(X, Y, Z, W) + \left(b + \frac{c}{4n-7}\right) [g(X, Z)S(Y, W) - g(Y, Z)S(X, W)] = 0. \quad (3.14)$$

Putting $X = e_i, Y = Ie_i, W = IW$ in the above equation and summing over $i, 1 \leq i \leq 4n$ and operating the result of the Theorem 3.3 we have

$$\left(b + \frac{c}{4n-7}\right) S(Z, W) = 0. \quad (3.15)$$

Then we have $S(Z, W) = 0$, for any $Z, W \in \chi(M)$, being the Lie algebra of vector fields on M . This completes the proof. $\square$

From Theorem 3.11 we have the following Corollary:

Corollary 3.12. A quasi- W_2 flat hyperKähler manifold is Ricci flat, provided $c \neq 0$.

The following examples are given in the paper [14]

Example 3.13. A trivial example is $\mathbb{H}^n$. However, in contrast to the Kähler case, $\mathbb{H}P_n$ is not hyperKähler and neither do its generic quaternionic submanifolds.

Example 3.14. In the particular case $n = 1$, then $SP_1 = SU_2$ in SO_4 , so a 4-dimensional Riemannian manifold is hyperKähler exactly when it is Kähler and Ricci flat. Specifically, this shows that any compact complex surface M of Kähler type with vanishing first Chern class is either a torus or simply connected and admits a unique complex-symplectic structure, i.e., is a so-called "K3-surface".

Example 3.15. A class of non-compact hyperKähler manifolds of real dimension 4 can be obtained by resolving the singularity of C^2/Γ for $\Gamma \subset SU_2$ a finite subgroup.

Example 3.16. Many examples of non-compact hyperKähler manifolds arise as moduli spaces of solutions to gauge-theoretic equations. The hyperKähler structure is obtained by a hyperKähler reduction from $\mathbb{H}^n$.

These results can be verified in these examples.

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